Parallel MATLAB at VT: Parallel For Loops

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9:00am - 10:00am
.......... NLI ..........

AOE: Department of Aerospace and Ocean Engineering
ARC: Advanced Research Computing
ICAM: Interdisciplinary Center for Applied Mathematics
Introduction

FMINCON Example

Executing a PARFOR Program

PRIME Example

Classification of variables

ODE_SWEEP Example

MD Example

Conclusion
In a previous lecture we discussed MATLAB’s Parallel Computing Toolbox (PCT), and the Distributed Computing Server (MDCS) that runs on Virginia Tech’s Ithaca cluster.

As noted previously there are three ways to write a parallel MATLAB program:

- suitable for loops can be made into parfor loops;
- the spmd statement can define cooperating synchronized processing;
- the task feature creates multiple independent programs.

Today we focus on parfor loops and on options for parallelism in MATLAB provided toolboxes.
Today’s Lecture: PARFOR

The simplest path to parallelism is the parfor statement, which indicates that a given for loop can be executed in parallel.

When the “client” MATLAB reaches such a loop, the iterations of the loop are automatically divided up among the workers, and the results gathered back onto the client.

Using parfor requires that the iterations are completely independent; the results must not depend on the order of execution. There are also restrictions on array-data access.

OpenMP implements a directive for ’parallel for loops’
Lecture #3: SPMD Wednesday, 5 November, 3:30-4:40pm

MATLAB can also work in a simplified kind of MPI model.

There is always a special “client” process.

Each worker process has its own memory and separate ID.

There is a single program, but it is divided into client and worker sections; the latter marked by special `spmd/end` statements.

Workers can “see” the client’s data; the client can access and change worker data.

The workers can also send messages to other workers.

OpenMP includes constructs similar to `spmd`.
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**FMINCON** is a popular MATLAB function available in the Optimization Toolbox. It finds a local minimizer of a real-valued function of several real variables with constraints:

\[
\min F(X) \text{ subject to:}
\]

\[
A \times X \leq B,
\]
\[
A_{eq} \times X = B_{eq} \quad \text{(linear constraints)}
\]
\[
C(X) \leq 0,
\]
\[
C_{eq}(X) = 0 \quad \text{(nonlinear constraints)}
\]
\[
L_B \leq X \leq U_B \quad \text{(bounds)}
\]

If no derivative (Jacobian) information is supplied by the user, then **FMINCON** uses finite differences to estimate these quantities. If \(F, C\) or \(C_{eq}\) are expensive to evaluate, the finite differencing can dominate the execution time.
An example using FMINCON involves a boat trying to cross a river against a current. The boat is given 10 minutes to make the crossing, and must try to land as far as possible upstream. In this unusual river, the current is zero midstream, negative above the x axis, and positive (helpful) below the x axis!
The correct solution takes maximum advantage of the favorable current, and then steers back hard to the land on the line $y = 1$. 
**FMINCON** uses an **options** structure that contains default settings. The user can modify these by calling the procedure **optimset**. The finite differencing process can be done in parallel if the user sets the appropriate option:

```matlab
options = optimset( optimset( 'fmincon' ), ... 
    'LargeScale','off', ... 
    'Algorithm', 'active-set', ... 
    'Display' , 'iter', ... 
    'UseParallel', 'Always');
```

```matlab
[ x_star, f_star, exit ] = fmincon ( h_cost, z0, ... 
    [], [], [], [], LB, UB, h_cnst, options );
```

In **version 2013a** and earlier, the user must invoke the **pool** (matlabpool) command to make workers available.
Matlab Toolboxes that employ PCT in ver 2013b

- Simulink
- Computational Biology
- Control System Design and Analysis
- Image Processing, Signal Processing
- Optimization
- Statistics

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Parallel MATLAB jobs can be run *directly*, that is, interactively.

The `parpool` command is used to reserve a given number of workers on the local (or perhaps remote) machine.

Once these workers are available, the user can type commands, run scripts, or evaluate functions, which contain `parfor` statements. The workers will cooperate in producing results.

Interactive parallel execution is great for desktop debugging of short jobs.

It’s an inefficient way to work on a cluster, because no one else can use the workers until you release them!

**Note:** Starting in R2013b, if you try to execute a parallel program and a pool of workers is not already open, MATLAB will open it for you. The pool of workers will then remain open for a time that can be specified under `Parallel → Parallel Preferences` (default is 30 minutes).
Parallel PARFOR MATLAB jobs can be run indirectly.

The **batch** command is used to specify a MATLAB code to be executed, to indicate any files that will be needed, and how many workers are requested.

The **batch** command starts the computation in the background. The user can work on other things, and collect the results when the job is completed.

The **batch** command works on the desktop, and can be set up to access ARC clusters (e.g. Ithaca).
INTRO: batch options

- **Workspace** — A 1-by-1 struct to define the workspace on the worker just before the script is called. The field names of the struct define the names of the variables, and the field values are assigned to the workspace variables. By default, this parameter has a field for every variable in the current workspace where batch is executed. This parameter supports only the running of scripts.

- **Profile** — A single string that is the name of a cluster profile to use to identify the cluster. If this option is omitted, the default profile is used to identify the cluster and is applied to the job and task properties.

- **AdditionalPaths** — A string or cell array of strings that defines paths to be added to the MATLAB® search path of the workers before the script or function executes. The default search path might not be the same on the workers as it is on the client; the path difference could be the result of different current working folders (pwd), platforms, or network file system access. The 'AdditionalPaths' property can assure that workers are looking in the correct locations for necessary code files, data files, model files, etc.

- **AttachedFiles** — A string or cell array of strings. Each string in the list identifies either a file or a folder, which gets transferred to the worker.

- **CurrentFolder** — A string indicating in what folder the script executes. There is no guarantee that this folder exists on the worker. The default value for this property is the cwd of MATLAB when the batch command is executed. If the string for this argument is '.', there is no change in folder before batch execution.

- **CaptureDiary** — A logical flag to indicate that the toolbox should collect the diary from the function call. See the diary function for information about the collected data. The default is true.

- **Pool** — An integer specifying the number of workers to make into a parallel pool for the job in addition to the worker running the batch job itself. The script or function uses this pool for execution of statements such as parfor and spmd that are inside the batch code. Because the pool requires N workers in addition to the worker running the batch, there must be at least \( N + 1 \) workers available on the cluster. You do not have to have a parallel pool already running to execute batch; and the new pool that batch creates is not related to a pool you might already have open. (See Run a Batch Parallel Loop.) The default value is 0, which causes the script or function to run on only the single worker without a parallel pool.
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For our next example, we want a simple computation involving a loop which we can set up to run for a long time.

We’ll choose a program that determines how many prime numbers there are between 1 and $N$.

If we want the program to run longer, we increase the variable $N$. Doubling $N$ multiplies the run time roughly by 4.
PRIME: The Sieve of Eratosthenes
function total = prime ( n )

%% PRIME returns the number of primes between 1 and N.

total = 0;

for i = 2 : n

    prime = 1;

    for j = 2 : i - 1
        if ( mod ( i, j ) == 0 )
            prime = 0;
        end
    end

    total = total + prime;
end

return
end
We can parallelize the loop whose index is $i$, replacing `for` by `parfor`. The computations for different values of $i$ are independent.

There is one variable that is not independent of the loops, namely `total`. This is simply computing a running sum (a `reduction variable`), and we only care about the final result. MATLAB is smart enough to be able to handle this summation in parallel.

To make the program parallel, we replace `for` by `parfor`. That’s all!

Beware - `reduction assignments` require care

% matlabpool ( 'open', 'local', 4) % old form
pool_obj = parpool('local', 4); % (R2013b)

n=50;

while ( n <= 5000000 )
    primes = prime_number_parfor ( n );
    fprintf ( 1, '__%8d__%8d\n', n, primes );
    n = n * 10;
end

%matlabpool ( 'close' )
delete(pool_obj);
PRIME: Timing

PRIME_PARFOR_RUN

Run PRIME_PARFOR with 0, 2, and 4 labs.

<table>
<thead>
<tr>
<th>N</th>
<th>1+0</th>
<th>1+2</th>
<th>1+4</th>
</tr>
</thead>
<tbody>
<tr>
<td>50000</td>
<td>0.13</td>
<td>0.10</td>
<td>0.08</td>
</tr>
<tr>
<td>500000</td>
<td>3.25</td>
<td>1.66</td>
<td>0.85</td>
</tr>
<tr>
<td>5000000</td>
<td>84.9</td>
<td>43.3</td>
<td>21.8</td>
</tr>
</tbody>
</table>
There are many thoughts that come to mind from these results!

This data suggests two conclusions:

*Parallelism doesn’t pay until your problem is big enough;*

AND

*Parallelism doesn’t pay until you have a decent number of workers.*
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## Classification: Variable Types in PARFOR Loops

<table>
<thead>
<tr>
<th>Classification</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Loop</td>
<td>Serves as a loop index for arrays</td>
</tr>
<tr>
<td>Sliced</td>
<td>An array whose segments are operated on by different iterations of the loop</td>
</tr>
<tr>
<td>Broadcast</td>
<td>A variable defined before the loop whose value is used inside the loop, but never assigned inside the loop</td>
</tr>
<tr>
<td>Reduction</td>
<td>Accumulates a value across iterations of the loop, regardless of iteration order</td>
</tr>
<tr>
<td>Temporary</td>
<td>Variable created inside the loop, but unlike sliced or reduction variables, not available outside the loop</td>
</tr>
</tbody>
</table>
CLASSIFICATION: an example

```
a = 0;
c = pi;
z = 0;
r = rand(1,10);
parfor i = 1:10
    a = i;
    z = z+i;
    b(i) = r(i);
    if i <= c
        d = 2*a;
    end
end
```

NB: "The range of a parfor statement must be increasing consecutive integers"

Trick Ques: What values do a, i, and d have after exiting the loop?
Sliced variables:

Characteristics of a **Sliced Variable**. A variable in a `parfor`-loop is **sliced** if it has all of the following characteristics. A description of each characteristic follows the list:

- **Type of First-Level Indexing** — The first level of indexing is either parentheses, ( ), or braces, { }.
- **Fixed Index Listing** — Within the first-level parenthesis or braces, the list of indices is the same for all occurrences of a given variable.
- **Form of Indexing** — Within the list of indices for the variable, exactly one index involves the loop variable.
- **Shape of Array** — In assigning to a **sliced** variable, the right-hand side of the assignment is not [ ] or ' ' (these operators indicate deletion of elements).
Allocating the loop indices

How are the *loop indices* distributed among the workers?

Run $ii=1:1000$ on 4 workers.

$\approx 63\%$ indices allocated in the first 4 *chunks*.

Indices then assigned in smaller chunks as a worker finishes.

Similar to *OpenMP*’s *Dynamic* assignment.
At least since **R2007a** basic **MATLAB** has incorporated multithreading

Many linear algebra functions (e.g. LU, QR, SVD) use multithreads


In the **PCT** each worker/lab runs a single thread

For some codes using `parfor` will increase the execution time
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Consider a favorite ordinary differential equation, which describes the motion of a spring-mass system:

\[ m\frac{d^2x}{dt^2} + b\frac{dx}{dt} + kx = f(t), \quad x(0) = 0, \; \dot{x}(0) = v. \]
Solutions of this equation describe oscillatory behavior; $x(t)$ swings back and forth, in a pattern determined by the parameters $m, b, k, f$ and the initial conditions.

Each choice of parameters defines a solution, and let us suppose that the quantity of interest is the maximum deflection $x_{\text{max}}$ that occurs for each solution.

We may wish to investigate the influence of $b$ and $k$ on this quantity, leaving $m$ fixed and $f$ zero.

So our computation might involve creating a plot of $x_{\text{max}}(b, k)$. 
ODE: Each Solution has a Maximum Value

- For $m = 5$, $b = 2$, $k = 2$, the maximum displacement is approximately 1.
- For $m = 5$, $b = 5$, $k = 5$, the maximum displacement is approximately 0.6.
Evaluating the implicit function $xmax(b, k)$ requires selecting a pair of values for the parameters $b$ and $k$, solving the ODE over a fixed time range, and determining the maximum value of $x$ that is observed. Each point in our graph will cost us a significant amount of work.

On the other hand, it is clear that each evaluation is completely independent, and can be carried out in parallel. Moreover, if we use a few shortcuts in MATLAB, the whole operation becomes quite straightforward!
m = 5.0;
bVals = 0.1 : 0.05 : 5;
kVals = 1.5 : 0.05 : 5;

[ bGrid, kGrid ] = meshgrid ( bVals, kVals );

peakVals = nan ( size ( kGrid ) );

tic;

parfor ij = 1 : numel ( kGrid )

    [ T, Y ] = ode45 ( @(t,y) ode_system ( t, y, m, bGrid(ij), ... kGrid(ij) ), [0, 25], [0, 1] );

    peakVals(ij) = max ( Y(:,1) );

end

toc;
ODE: PARPOOL or BATCH Execution

```matlab
pool_obj = parpool('local', 4);
ode_sweep_parfor
delete(pool_obj)
ode_sweep_display

job = batch ( ...
    'ode_sweep_script', ...
    'Profile', 'local', ...
    'AttachedFiles', {'ode_system.m'}, ...
    'pool', 4 );
wait ( job );
load ( job );
ode_sweep_display
delete ( job ) % destroy prior to R2012a
```
% Display the results.

figure;

surf ( bVals, kVals, peakVals, 'EdgeColor', 'Interp', 'FaceColor', 'Interp' );

title ( 'Results of ODE Parameter Sweep' )
xlabel ( 'Damping B' );
ylabel ( 'Stiffness K' );
zlabel ( 'Peak Displacement' );
view ( 50, 30 )
ODE: A Parameterized Problem

Results of ODE Parameter Sweep

- Peak Displacement
- Damping B
- Stiffness K
In the PRIME program, the \texttt{parfor} loop was invoked in the outer loop; in each iteration there is a reasonable workload/.

In the ODE parameter sweep, we have several thousand IVP’s to solve, but we could solve them in any order, on various computers, or any way we wanted to. All that was important was that when the computations were completed, every value $x_{max}(b, x)$ had been computed.

This kind of loosely-coupled problem can be treated as a \textit{task computing} problem, wherein \texttt{MATLAB} can treat this problem as a collection of many little tasks to be computed in an arbitrary fashion and assembled at the end.
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MD: A Molecular Dynamics Simulation

Compute the positions and velocities of $N$ particles at a sequence of times. The particles exert a weak attractive force on each other.
The MD program runs a simple molecular dynamics simulation.

There are $N$ molecules being simulated.

The program runs a long time; a parallel version would run faster.

There are many `for` loops in the program that we might replace by `parfor`, but it is a mistake to try to parallelize everything!

**Matlab** has a `profile` command that can report where the CPU time was spent - which is where we should try to parallelize.
MD: Profile the Sequential Code

```plaintext
>> profile on
>> md
>> profile viewer
```

<table>
<thead>
<tr>
<th>Step</th>
<th>Potential Energy</th>
<th>Kinetic Energy</th>
<th>((P+K-E_0)/E_0)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>498108.113974</td>
<td>0.000000</td>
<td>0.000000e+00</td>
</tr>
<tr>
<td>2</td>
<td>498108.113974</td>
<td>0.000009</td>
<td>1.794265e-11</td>
</tr>
<tr>
<td>...</td>
<td>...</td>
<td>...</td>
<td>...</td>
</tr>
<tr>
<td>9</td>
<td>498108.111972</td>
<td>0.002011</td>
<td>1.794078e-11</td>
</tr>
<tr>
<td>10</td>
<td>498108.111400</td>
<td>0.002583</td>
<td>1.793996e-11</td>
</tr>
</tbody>
</table>

CPU time = 415.740000 seconds.
Wall time = 378.828021 seconds.
### MD: Where is Execution Time Spent?

<table>
<thead>
<tr>
<th>Function Name</th>
<th>Calls</th>
<th>Total Time</th>
<th>Self Time*</th>
<th>Total Time Plot</th>
</tr>
</thead>
<tbody>
<tr>
<td>md</td>
<td>1</td>
<td>415.847 s</td>
<td>0.096 s</td>
<td></td>
</tr>
<tr>
<td>compute</td>
<td>11</td>
<td>415.459 s</td>
<td>410.703 s</td>
<td></td>
</tr>
<tr>
<td>repmat</td>
<td>11000</td>
<td>4.755 s</td>
<td>4.755 s</td>
<td></td>
</tr>
<tr>
<td>timestamp</td>
<td>2</td>
<td>0.267 s</td>
<td>0.108 s</td>
<td></td>
</tr>
<tr>
<td>datestr</td>
<td>2</td>
<td>0.130 s</td>
<td>0.040 s</td>
<td></td>
</tr>
<tr>
<td>timefun/private/formatdate</td>
<td>2</td>
<td>0.084 s</td>
<td>0.084 s</td>
<td></td>
</tr>
<tr>
<td>update</td>
<td>10</td>
<td>0.019 s</td>
<td>0.019 s</td>
<td></td>
</tr>
<tr>
<td>datevec</td>
<td>2</td>
<td>0.017 s</td>
<td>0.017 s</td>
<td></td>
</tr>
<tr>
<td>now</td>
<td>2</td>
<td>0.013 s</td>
<td>0.001 s</td>
<td></td>
</tr>
<tr>
<td>datenum</td>
<td>4</td>
<td>0.012 s</td>
<td>0.012 s</td>
<td></td>
</tr>
<tr>
<td>datestr&gt;getdateform</td>
<td>2</td>
<td>0.005 s</td>
<td>0.005 s</td>
<td></td>
</tr>
<tr>
<td>initialize</td>
<td>1</td>
<td>0.005 s</td>
<td>0.005 s</td>
<td></td>
</tr>
<tr>
<td>etime</td>
<td>2</td>
<td>0.002 s</td>
<td>0.002 s</td>
<td></td>
</tr>
</tbody>
</table>

**Self time** is the time spent in a function excluding the time spent in its child functions. Self time also includes overhead resulting from the process of profiling.
function [ f, pot, kin ] = compute ( np, nd, pos, vel, mass )

f = zeros ( nd, np );
pot = 0.0;

for i = 1 : np
    for j = 1 : np
        if ( i ~= j )
            rij(1:nd) = pos(1:nd, i) − pos(1:nd, j);
            d = sqrt ( sum ( rij(1:nd).^2 ) );
            d2 = min ( d, pi / 2.0 );
            pot = pot + 0.5 * sin ( d2 ) * sin ( d2 );
            f(1:nd,i) = f(1:nd,i) − rij(1:nd) * sin ( 2.0 * d2 ) / d;
        end
    end
end

kin = 0.5 * mass * sum ( vel(1:nd,1:np).^2 );

return
function [ f, pot, kin ] = compute ( np, nd, pos, vel, mass )

f = zeros ( nd, np );
pot = 0.0;
pi2 = pi / 2.0;

parfor i = 1 : np
    Ri = pos - repmat ( pos(:,i), 1, np );% array of vectors to 'i'
    D = sqrt ( sum ( Ri.^2 ) );% array of distances
    Ri = Ri(:, ( D > 0.0 ) );% save only pos values
    D = D( D > 0.0 );% save only pos values
    D2 = D .* ( D <= pi2 ) + pi2*( D > pi2 );% truncate the potential
    pot = pot + 0.5 * sum ( sin ( D2 ).^2 );% accumulate pot. energy
    f(:,i) = Ri * ( sin ( 2*D2 ) ./ D )';% force on particle
end

% Compute kinetic energy.
kin = 0.5 * mass * sum ( diag ( vel' * vel ) );

return
end
The compute function fills the force vector \( f(i) \) using a for loop.

Iteration \( i \) computes the force on particle \( i \), determining the distance to each particle \( j \), squaring, truncating, taking the sine.

The computation for each particle is “independent”; nothing computed in one iteration is needed by, nor affects, the computation in another iteration. We could compute each value on a separate worker, at the same time.

The Matlab command parfor will distribute the iterations of this loop across the available workers.

Tricky question: Could we parallelize the \( j \) loop instead?

Tricky question: Could we parallelize both loops?
Replacing “for i” by “parfor i”, here is our speedup:
Parallel execution gives a huge improvement in this example.

There is some overhead in starting up the parallel process, and in transferring data to and from the workers each time a `parfor` loop is encountered. So we should not simply try to replace every `for` loop with `parfor`.

That’s why we first searched for the function that was using most of the execution time.

The `parfor` command is the simplest way to make a parallel program, but in the next lecture we will see some alternatives.
We were only able to parallelize the loop because the iterations were independent, that is, the results did not depend on the order in which the iterations were carried out.

In fact, to use MATLAB’s `parfor` in this case requires some extra conditions, which are discussed in the PCT User’s Guide. Briefly, `parfor` is usable when vectors and arrays that are modified in the calculation can be divided up into distinct slices, so that each slice is only needed for one iteration.

This is a stronger requirement than independence of order!

Trick question: Why was the scalar value POT acceptable?
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In the **FMINCON** example, all we had to do to take advantage of parallelism was set an option (and possibly make sure some workers were available).

By timing the PRIME example, we saw that it is inefficient to work on small problems, or with only a few processors.

In the ODE_SWEEP example, the loop we modified was not a small internal loop, but a big “outer” loop that defined the whole calculation.

In the MD example, we did a profile first to identify where the work was.
We only briefly mentioned the limitations of the `parfor` statement.

You can look in the User’s Guide for some more information on when you are allowed to turn a `for` loop into a `parfor` loop. It’s not as simple as just knowing that the loop iterations are independent. **Matlab** has concerns about data usage as well.

**Matlab**s built in program editor (`mlint`) knows all about the rules for using `parfor`. You can experiment by changing a `for` to `parfor`, and the editor will immediately complain to you if there is a reason that **Matlab** will not accept a `parfor` version of the loop.
Virginia Tech has a limited number of concurrent MATLAB licenses, and including the Parallel Computing Toolbox.

Since Fall 2011, the PCT is included with the student license.

Run `ver` in the MATLAB Command Window to see what licenses you have available.

If you don’t have a multicore machine, you won’t see any speedup, but you may still be able to run some ‘parallel’ programs.
CONCLUSION: Desktop-to-Ithaca Submission

- If you want to work with parallel MATLAB on ARC resources, you must first get an account. Go to http://www.arc.vt.edu/account
  Log in (PID and password), select the systems you want to work with and MATLAB in the Software section, and submit.

- Steps to set up submission from your desktop include:
  1. Download and add some files to your MATLAB directory
  2. Run a script to create a new profile on your desktop.

A new cluster profile (e.g. ithaca_R2015a) will be created that can be used in batch().
These steps are described in detail at: http://www.arc.vt.edu/matlabremote
There is a local LISTSERV for people interested in *Matlab* on the Virginia Tech campus. We try **not** to post messages here unless we really consider them of importance!

Important messages include information about workshops, special *Mathworks* events, and other issues affecting *Matlab* users.

To subscribe to the *Mathworks* listserver, send a blank email to:

```
mathworks-g+subscribe@vt.edu
```

The subject and body of the message should both be empty.
**CONCLUSION: Where is it?**

- **MATLAB** Parallel Computing Toolbox Product Documentation
  
  http://www.mathworks.com/help/toolbox/distcomp/

- Gaurav Sharma, Jos Martin,
  

- An **Adobe** PDF with these notes, along with a zipped-folder containing the **MATLAB** codes can be downloaded from the VT-arc web-site at

  http://www.arc.vt.edu/matlab#resources
Please complete the evaluation form

Thanks